



## Fractional Order Differential Equations Involving Caputo Derivative

Zoubir Dahmani<sup>a,\*</sup>, Louiza Tabharit<sup>b</sup>

<sup>a</sup>Laboratory LPAM, Faculty SEI, UMAB University, Algeria

<sup>b</sup>Department Maths-Info, Faculty SEI, UMAB University, Algeria

---

### Abstract

In this paper, the Banach contraction principle and Schaefer theorem are applied to establish new results for the existence and uniqueness of solutions for some Caputo fractional differential equations. Some examples are also discussed to illustrate the main results.

**Keywords:** Caputo derivative, Banach fixed point theorem, Fractional differential equations.

**2010 MSC:** 34A34, 34B10.

---

### 1. Introduction

The theory of fractional differential equations has excited in recent years a considerable interest both in mathematics and in applications, (see (Bengrine & Dahmani, 2012; Delbosco & Rodino, 1996; Diethelm & Walz, 1998; El-Sayed, 1998)). In particular, existence and uniqueness of solutions for fractional differential equations have attracted the attention of many mathematicians (Diethelm & Ford, 2002; Houas & Dahmani, 2013; Zhang, 2011; Ntouyas, 2012; Su, 2009; Yang, 2012; Zhang, 2011).

This paper deals with the existence and uniqueness of solutions to the following problem

$$\begin{aligned} D^\alpha x(t) + f(t, y(t), D^\delta y(t)) &= 0, t \in J, \\ D^\beta y(t) + g(t, x(t), D^\sigma x(t)) &= 0, t \in J, \\ x(0) = y(0) = 0, x(1) - \lambda_1 x(\eta) &= 0, y(1) - \lambda_1 y(\eta) = 0, \\ x''(0) = y''(0) = 0, x''(1) - \lambda_2 x''(\xi) &= 0, y''(1) - \lambda_2 y''(\xi) = 0, \end{aligned} \quad (1.1)$$

---

\*Corresponding author

Email addresses: [zzdahmani@yahoo.fr](mailto:zzdahmani@yahoo.fr) (Zoubir Dahmani), [lz.tahbarit@yahoo.fr](mailto:lz.tahbarit@yahoo.fr) (Louiza Tabharit)

where  $D^\alpha, D^\beta, D^\delta$  and  $D^\sigma$ , are the Caputo fractional derivatives,  $3 < \alpha, \beta \leq 4, \delta \leq \alpha - 1, \sigma \leq \beta - 1, 0 < \xi, \eta < 1, J = [0, 1], \lambda_1, \lambda_2$  are real constants satisfying  $\lambda_1 \eta \neq 1, \lambda_2 \xi \neq 1$  and  $f, g$  are two functions which will be specified later.

This paper is organized as follows: In section 2, we present some preliminaries and lemmas. In section 3, we present our main results for the existence and uniqueness of solutions of (1.1). In section 4, some examples are treated to illustrate our results.

## 2. Preliminaries

To present our main results, we need the the following two definitions:

**Definition 2.1.** The Riemann-Liouville fractional integral operator of order  $\alpha \geq 0$ , for a continuous function  $f$  on  $[0, \infty[$  is defined as:

$$J^\alpha f(t) = \frac{1}{\Gamma(\alpha)} \int_0^t (t - \tau)^{\alpha-1} f(\tau) d\tau, \alpha > 0, \quad (2.1)$$

$$J^0 f(t) = f(t),$$

where  $\Gamma(\alpha) := \int_0^\infty e^{-u} u^{\alpha-1} du$ .

**Definition 2.2.** The fractional derivative of  $f \in C^n([0, \infty[)$  in the Caputo's sense is defined as:

$$D^\alpha f(t) = \frac{1}{\Gamma(n - \alpha)} \int_0^t (t - \tau)^{n-\alpha-1} f^{(n)}(\tau) d\tau, n - 1 < \alpha, n \in \mathbb{N}^*. \quad (2.2)$$

More details about fractional calculus can be found in (Mainardi, 1997; Podlubny et al., 2002).

We need also to introduce the spaces:

$X = \{x : x \in C([0, 1]), D^\sigma x \in C([0, 1])\}$  and  $Y = \{y : y \in C([0, 1]), D^\delta y \in C([0, 1])\}$ . For these spaces, we associate respectively the norms  $\|x\|_X = \|x\| + \|D^\sigma x\|; \|x\| = \sup_{t \in J} |x(t)|, \|D^\sigma x\| = \sup_{t \in J} |D^\sigma x(t)|$  and  $\|y\|_Y = \|y\| + \|D^\delta y\|; \|y\| = \sup_{t \in J} |y(t)|, \|D^\delta y\| = \sup_{t \in J} |D^\delta y(t)|$ . It is clear that,  $(X, \|\cdot\|_X)$  and  $(Y, \|\cdot\|_Y)$ , are two Banach spaces.

Also,  $(X \times Y, \|(x, y)\|_{X \times Y})$  is a Banach space. Its norm is given by  $\|(x, y)\|_{X \times Y} = \|x\|_X + \|y\|_Y$ .

The following lemmas are crucial for our main results (Kilbas & Marzan, 2005; Lakshmikantham & Vatsala, 2008):

**Lemma 2.1.** For  $\alpha > 0$ , the general solution of the equation  $D^\alpha x(t) = 0$  is given by

$$x(t) = c_0 + c_1 t + c_2 t^2 + \dots + c_{n-1} t^{n-1}, \quad (2.3)$$

where  $c_i \in \mathbb{R}, i = 0, 1, 2, \dots, n - 1, n = [\alpha] + 1$ .

**Lemma 2.2.**

$$J^\alpha D^\alpha x(t) = x(t) + c_0 + c_1 t + c_2 t^2 + \dots + c_{n-1} t^{n-1}, \quad (2.4)$$

for some  $c_i \in \mathbb{R}, i = 0, 1, 2, \dots, n - 1, n = [\alpha] + 1$ .

We prove also the following lemma which is needed to present the integral solution for the problem (1.1):

**Lemma 2.3.** Let  $h \in C([0, 1])$ ,  $t \in J$ ,  $3 < \alpha \leq 4$ . Then the solution of the equation

$$D^\alpha x(t) + h(t) = 0, \quad (2.5)$$

where,

$$\begin{aligned} x(0) &= 0, x(1) - \lambda_1 x(\eta) = 0, \\ x''(0) &= 0, x''(1) - \lambda_2 x''(\xi) = 0 \end{aligned} \quad (2.6)$$

is given by the following expression

$$\begin{aligned} x(t) &= -\frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} h(s, y(s), D^\delta y(s)) ds \\ &+ \frac{\lambda_1 t}{(\lambda_1 \eta - 1) \Gamma(\alpha)} \int_0^\eta (\eta-s)^{\alpha-1} h(s, y(s), D^\delta y(s)) ds \\ &- \frac{1}{(\lambda_1 \eta - 1) \Gamma(\alpha)} \int_0^1 (1-s)^{\alpha-1} h(s, y(s), D^\delta y(s)) ds \\ &+ \frac{(\lambda_2 - \lambda_2 \lambda_1 \eta^3) t + (\lambda_2 \lambda_1 \eta - \lambda_2) t^3}{6(\lambda_1 \eta - 1)(\lambda_2 \xi - 1) \Gamma(\alpha - 2)} \int_0^\xi (\xi-s)^{\alpha-3} h(s, y(s), D^\delta y(s)) ds \\ &- \frac{(1 - \lambda_1 \eta^3) t + (\lambda_1 \eta - 1) t^3}{6(\lambda_1 \eta - 1)(\lambda_2 \xi - 1) \Gamma(\alpha - 2)} \int_0^1 (1-s)^{\alpha-3} h(s, y(s), D^\delta y(s)) ds. \end{aligned} \quad (2.7)$$

**Proof:** Let  $c_i \in \mathbb{R}$ ,  $i = 0, 1, 2, 3$ . Then by lemmas 2.1, 2.2, the general solution of (2.5) can be written as:

$$x(t) = -\frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} h(s) ds - c_0 - c_1 t - c_2 t^2 - c_3 t^3. \quad (2.8)$$

Using (2.6), we immediately get  $c_0 = c_2 = 0$ . On the other hand, we have

$$\begin{aligned} c_1 &= -\frac{\lambda_1}{(\lambda_1 \eta - 1) \Gamma(\alpha)} \int_0^\eta (\eta-s)^{\alpha-1} h(s) ds + \frac{1}{(\lambda_1 \eta - 1) \Gamma(\alpha)} \int_0^1 (1-s)^{\alpha-1} h(s) ds \\ &- \frac{\lambda_2 (1 - \lambda_1 \eta^3)}{6(\lambda_1 \eta - 1)(\lambda_2 \xi - 1) \Gamma(\alpha - 2)} \int_0^\xi (\xi-s)^{\alpha-3} h(s) ds \\ &+ \frac{(1 - \lambda_1 \eta)}{6(\lambda_1 \eta - 1)(\lambda_2 \xi - 1) \Gamma(\alpha - 2)} \int_0^1 (1-s)^{\alpha-3} h(s) ds. \end{aligned} \quad (2.9)$$

To obtain the value of  $c_3$ , we remark that

$$c_3 = -\frac{\lambda_2}{6(\lambda_2 \xi - 1) \Gamma(\alpha - 2)} \int_0^\xi (\xi-s)^{\alpha-3} h(s) ds + \frac{1}{6(\lambda_2 \xi - 1) \Gamma(\alpha - 2)} \int_0^1 (1-s)^{\alpha-3} g(s) ds. \quad (2.10)$$

Finally, substituting the values of  $c_1$  and  $c_3$  in (2.8), we obtain (2.7).

### 3. Main results

We begin by introducing the quantities:

$$\begin{aligned} N_1 &= \frac{|\lambda_1\eta-1|+|\lambda_1|\eta^{\alpha+1}}{|\lambda_1\eta-1|\Gamma(\alpha+1)} + \frac{(|\lambda_2-\lambda_2\lambda_1\eta^3|+|\lambda_2\lambda_1\eta-\lambda_2|)\xi^{\alpha-2}+|1-\lambda_1\eta^3|+|\lambda_1\eta-1|}{6|\lambda_1\eta-1||\lambda_2\xi-1|\Gamma(\alpha-1)}, \\ N_2 &= \frac{1}{\Gamma(\alpha-\sigma+1)} + \frac{|\lambda_1|\eta^{\alpha+1}}{|\lambda_1\eta-1|\Gamma(\alpha+1)\Gamma(2-\sigma)} + \frac{|\lambda_2-\lambda_2\lambda_1\eta^3|\xi^{\alpha-2}+|1-\lambda_1\eta^3|}{6|\lambda_1\eta-1||\lambda_2\xi-1|\Gamma(\alpha-1)\Gamma(2-\sigma)} \\ &\quad + \frac{|\lambda_2\lambda_1\eta-\lambda_2|\xi^{\alpha-2}+|\lambda_1\eta-1|}{|\lambda_1\eta-1||\lambda_2\xi-1|\Gamma(\alpha-1)\Gamma(4-\sigma)}, \\ N_3 &= \frac{|\lambda_1\eta-1|+|\lambda_1|\eta^{\beta+1}}{|\lambda_1\eta-1|\Gamma(\beta+1)} + \frac{(|\lambda_2-\lambda_2\lambda_1\eta^3|+|\lambda_2\lambda_1\eta-\lambda_2|)\xi^{\beta-2}+|1-\lambda_1\eta^3|+|\lambda_1\eta-1|}{6|\lambda_1\eta-1||\lambda_2\xi-1|\Gamma(\beta-1)}, \\ N_4 &= \frac{1}{\Gamma(\beta-\delta+1)} + \frac{|\lambda_1|\eta^{\beta+1}}{|\lambda_1\eta-1|\Gamma(\beta+1)\Gamma(2-\delta)} + \frac{|\lambda_2-\lambda_2\lambda_1\eta^3|\xi^{\beta-2}+|1-\lambda_1\eta^3|}{6|\lambda_1\eta-1||\lambda_2\xi-1|\Gamma(\beta-1)\Gamma(2-\delta)} \\ &\quad + \frac{|\lambda_2\lambda_1\eta-\lambda_2|\xi^{\beta-2}+|\lambda_1\eta-1|}{|\lambda_1\eta-1||\lambda_2\xi-1|\Gamma(\beta-1)\Gamma(4-\delta)}. \end{aligned}$$

We impose also the hypotheses:

(H1) : The functions  $f, g : [0, 1] \times \mathbb{R}^2 \rightarrow \mathbb{R}$  are continuous.

(H2) : There exist non negative functions  $a_i, b_i \in C([0, 1])$ ,  $i = 1, 2$  such that for all  $t \in [0, 1]$  and  $(x_1, y_1), (x_2, y_2) \in \mathbb{R}^2$ , the inequalities

$$\begin{aligned} |f(t, x_1, y_1) - f(t, x_2, y_2)| &\leq a_1(t)|x_1 - x_2| + b_1(t)|y_1 - y_2|, \\ |g(t, x_1, y_1) - g(t, x_2, y_2)| &\leq a_2(t)|x_1 - x_2| + b_2(t)|y_1 - y_2|, \end{aligned} \quad (3.1)$$

are valid, and

$$\omega_1 = \sup_{t \in J} a_1(t), \omega_2 = \sup_{t \in J} b_1(t), \varpi_1 = \sup_{t \in J} a_2(t), \varpi_2 = \sup_{t \in J} b_2(t).$$

(H3) : There exist positive constants  $L_1$  and  $L_2$  such that

$$|f(t, x, y)| \leq L_1, |g(t, x, y)| \leq L_2 \text{ for each } t \in J \text{ and all } x, y \in \mathbb{R}.$$

Our first main result is given by the following theorem:

**Theorem 3.1.** Assume that (H2) holds and suppose that

$$(N_1 + N_2)(\omega_1 + \omega_2) + (N_3 + N_4)(\varpi_1 + \varpi_2) < 1. \quad (3.2)$$

Then the problem (1.1) has a unique solution on  $J$ .

**Proof:** We apply Banach fixed point theorem. So, we consider the operator  $\phi : X \times Y \rightarrow X \times Y$  defined by:

$$\phi(x, y)(t) := (\phi_1 y(t), \phi_2 x(t)), \quad (3.3)$$

where

$$\begin{aligned} \phi_{1y}(t) : &= -\frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} f(s, y(s), D^\delta y(s)) ds \\ &+ \frac{\lambda_1 t}{(\lambda_1 \eta - 1) \Gamma(\alpha)} \int_0^\eta (\eta-s)^{\alpha-1} f(s, y(s), D^\delta y(s)) ds \\ &- \frac{1}{(\lambda_1 \eta - 1) \Gamma(\alpha)} \int_0^1 (1-s)^{\alpha-1} f(s, y(s), D^\delta y(s)) ds \\ &+ \frac{(\lambda_2 - \lambda_2 \lambda_1 \eta^3)t + (\lambda_2 \lambda_1 \eta - \lambda_2)t^3}{6(\lambda_1 \eta - 1)(\lambda_2 \xi - 1)\Gamma(\alpha-2)} \int_0^\xi (\xi-s)^{\alpha-3} f(s, y(s), D^\delta y(s)) ds \\ &- \frac{(1 - \lambda_1 \eta^3)t + (\lambda_1 \eta - 1)t^3}{6(\lambda_1 \eta - 1)(\lambda_2 \xi - 1)\Gamma(\alpha-2)} \int_0^1 (1-s)^{\alpha-3} f(s, y(s), D^\delta y(s)) ds, \end{aligned} \quad (3.4)$$

and

$$\begin{aligned} \phi_{2x}(t) : &= -\frac{1}{\Gamma(\beta)} \int_0^t (t-s)^{\beta-1} g(s, x(s), D^\sigma x(s)) ds \\ &+ \frac{\lambda_1 t}{(\lambda_1 \eta - 1) \Gamma(\beta)} \int_0^\eta (\eta-s)^{\beta-1} g(s, x(s), D^\sigma x(s)) ds \\ &- \frac{1}{(\lambda_1 \eta - 1) \Gamma(\beta)} \int_0^1 (1-s)^{\beta-1} g(s, x(s), D^\sigma x(s)) ds \\ &+ \frac{(\lambda_2 - \lambda_2 \lambda_1 \eta^3)t + (\lambda_2 \lambda_1 \eta - \lambda_2)t^3}{6(\lambda_1 \eta - 1)(\lambda_2 \xi - 1)\Gamma(\beta-2)} \int_0^\xi (\xi-s)^{\beta-3} g(s, x(s), D^\sigma x(s)) ds \\ &- \frac{(1 - \lambda_1 \eta^3)t + (\lambda_1 \eta - 1)t^3}{6(\lambda_1 \eta - 1)(\lambda_2 \xi - 1)\Gamma(\beta-2)} \int_0^1 (1-s)^{\beta-3} g(s, x(s), D^\sigma x(s)) ds. \end{aligned} \quad (3.5)$$

And we shall prove that  $\phi$  is a contraction mapping.

Let  $(x, y), (x_1, y_1) \in X \times Y$ . Then, for each  $t \in J$ , we have:

$$\begin{aligned} |\phi_{1y}(t) - \phi_{1y_1}(t)| &\leq \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} \left| f(s, y(s), D^\delta y(s)) - f(s, y_1(s), D^\delta y_1(s)) \right| ds \\ &+ \frac{|\lambda_1|t}{|\lambda_1 \eta - 1| \Gamma(\alpha)} \int_0^\eta (\eta-s)^{\alpha-1} \left| f(s, y(s), D^\delta y(s)) - f(s, y_1(s), D^\delta y_1(s)) \right| ds \\ &+ \frac{t}{|\lambda_1 \eta - 1| \Gamma(\alpha)} \int_0^1 (1-s)^{\alpha-1} \left| f(s, y(s), D^\delta y(s)) - f(s, y_1(s), D^\delta y_1(s)) \right| ds \\ &+ \frac{|\lambda_2 - \lambda_2 \lambda_1 \eta^3|t + |\lambda_2 \lambda_1 \eta - \lambda_2|t^3}{6|\lambda_1 \eta - 1| |\lambda_2 \xi - 1| \Gamma(\alpha-2)} \int_0^\xi (\xi-s)^{\alpha-3} \left| f(s, y(s), D^\delta y(s)) - f(s, y_1(s), D^\delta y_1(s)) \right| ds \\ &+ \frac{|1 - \lambda_1 \eta^3|t + |\lambda_1 \eta - 1|t^3}{6|\lambda_1 \eta - 1| |\lambda_2 \xi - 1| \Gamma(\alpha-2)} \int_0^1 (1-s)^{\alpha-3} \left| f(s, y(s), D^\delta y(s)) - f(s, y_1(s), D^\delta y_1(s)) \right| ds. \end{aligned} \quad (3.6)$$

Thanks to (H2), we obtain

$$\begin{aligned}
 |\phi_{1y}(t) - \phi_{1y_1}(t)| \leq & \frac{(|\lambda_1\eta-1|+|\lambda_1|\eta^\alpha+1)(\omega_1\|y-y_1\|+\omega_2\|D^\delta y-D^\delta y_1\|)}{|\lambda_1\eta-1|\Gamma(\alpha+1)} \\
 & + \frac{[(|\lambda_2-\lambda_2\lambda_1\eta^3|+|\lambda_2\lambda_1\eta-\lambda_2|)\xi^{\alpha-2}+|1-\lambda_1\eta^3|+|\lambda_1\eta-1|](\omega_1\|y-y_1\|+\omega_2\|D^\delta y-D^\delta y_1\|)}{6|\lambda_1\eta-1|\|\lambda_2\xi-1\|\Gamma(\alpha-1)}.
 \end{aligned} \quad (3.7)$$

Consequently,

$$|\phi_{1y}(t) - \phi_{1y_1}(t)| \leq N_1 (\omega_1 + \omega_2) (\|y - y_1\| + \|D^\delta y - D^\delta y_1\|), \quad (3.8)$$

Hence,

$$\|\phi_1(y) - \phi_1(y_1)\| \leq N_1 (\omega_1 + \omega_2) (\|y - y_1\| + \|D^\delta y - D^\delta y_1\|). \quad (3.9)$$

We have also,

$$\begin{aligned}
 |D^\sigma \phi_{1y}(t) - D^\sigma \phi_{1y_1}(t)| \leq & \frac{1}{\Gamma(\alpha-\sigma)} \int_0^t (t-s)^{\alpha-\sigma-1} |f(s, y(s), D^\delta y(s)) - f(s, y_1(s), D^\delta y_1(s))| ds \\
 & + \frac{|\lambda_1|t^{1-\sigma}}{|\lambda_1\eta-1|\Gamma(\alpha)\Gamma(2-\sigma)} \int_0^\eta (\eta-s)^{\alpha-1} |f(s, y(s), D^\delta y(s)) - f(s, y_1(s), D^\delta y_1(s))| ds \\
 & + \frac{t^{1-\sigma}}{(|\lambda_1\eta-1|)\Gamma(\alpha)\Gamma(2-\sigma)} \int_0^1 (1-s)^{\alpha-1} |f(s, y(s), D^\delta y(s)) - f(s, y_1(s), D^\delta y_1(s))| ds \\
 & + \left( \frac{|\lambda_2-\lambda_2\lambda_1\eta^3|t^{1-\sigma}}{6|\lambda_1\eta-1|\|\lambda_2\xi-1\|\Gamma(\alpha-2)\Gamma(2-\sigma)} + \frac{|\lambda_2\lambda_1\eta-\lambda_2|t^{3-\sigma}}{|\lambda_1\eta-1|\|\lambda_2\xi-1\|\Gamma(\alpha-2)\Gamma(4-\sigma)} \right) \int_0^\xi (\xi-s)^{\alpha-3} |f(s, y(s), D^\delta y(s)) - f(s, y_1(s), D^\delta y_1(s))| ds \\
 & + \left( \frac{|1-\lambda_1\eta^3|t^{1-\sigma}}{6|\lambda_1\eta-1|\|\lambda_2\xi-1\|\Gamma(\alpha-2)\Gamma(2-\sigma)} + \frac{|\lambda_1\eta-1|t^{3-\sigma}}{|\lambda_1\eta-1|\|\lambda_2\xi-1\|\Gamma(\alpha-2)\Gamma(4-\sigma)} \right) \int_0^1 (1-s)^{\alpha-3} |f(s, y(s), D^\delta y(s)) - f(s, y_1(s), D^\delta y_1(s))| ds.
 \end{aligned} \quad (3.10)$$

By (H2), yields

$$\begin{aligned}
 |D^\sigma \phi_{1y}(t) - D^\sigma \phi_{1y_1}(t)| \leq & \frac{(\omega_1+\omega_2)(\|y-y_1\|+\|D^\delta y-D^\delta y_1\|)}{\Gamma(\alpha-\sigma+1)} \\
 & + \frac{(\omega_1+\omega_2)[|\lambda_1|\eta^\alpha+1](\|y-y_1\|+\|D^\delta y-D^\delta y_1\|)}{|\lambda_1\eta-1|\Gamma(\alpha+1)\Gamma(2-\sigma)} \\
 & + \frac{(\omega_1+\omega_2)[|\lambda_2-\lambda_2\lambda_1\eta^3|\xi^{\alpha-2}+|1-\lambda_1\eta^3|](\|y-y_1\|+\|D^\delta y-D^\delta y_1\|)}{6|\lambda_1\eta-1|\|\lambda_2\xi-1\|\Gamma(\alpha-1)\Gamma(2-\sigma)} \\
 & + \frac{(\omega_1+\omega_2)[|\lambda_2\lambda_1\eta-\lambda_2|\xi^{\alpha-2}+|\lambda_1\eta-1|](\|y-y_1\|+\|D^\delta y-D^\delta y_1\|)}{|\lambda_1\eta-1|\|\lambda_2\xi-1\|\Gamma(\alpha-1)\Gamma(4-\sigma)}.
 \end{aligned} \quad (3.11)$$

This implies that,

$$\begin{aligned}
 |D^\sigma \phi_{1y}(t) - D^\sigma \phi_{1y_1}(t)| \leq & \left[ \frac{(\omega_1+\omega_2)}{\Gamma(\alpha-\sigma+1)} + \frac{\omega_1(\omega_1+\omega_2)[|\lambda_1|\eta^\alpha+1]}{|\lambda_1\eta-1|\Gamma(\alpha+1)\Gamma(2-\sigma)} \right] (\|y - y_1\| + \|D^\delta y - D^\delta y_1\|) \\
 & + \left[ \frac{(\omega_1+\omega_2)[|\lambda_2-\lambda_2\lambda_1\eta^3|\xi^{\alpha-2}+|1-\lambda_1\eta^3|]}{6|\lambda_1\eta-1|\|\lambda_2\xi-1\|\Gamma(\alpha-1)\Gamma(2-\sigma)} + \frac{(\omega_1+\omega_2)[|\lambda_2\lambda_1\eta-\lambda_2|\xi^{\alpha-2}+|\lambda_1\eta-1|]}{|\lambda_1\eta-1|\|\lambda_2\xi-1\|\Gamma(\alpha-1)\Gamma(4-\sigma)} \right] (\|y - y_1\| + \|D^\delta y - D^\delta y_1\|).
 \end{aligned} \quad (3.12)$$

Therefore,

$$\left| D^\sigma \phi_1 y(t) - D^\sigma \phi_1 y_1(t) \right| \leq N_2 (\omega_1 + \omega_2) \left( \|y - y_1\| + \left\| D^\delta y - D^\delta y_1 \right\| \right). \quad (3.13)$$

Consequently,

$$\left\| D^\sigma \phi_1(y) - D^\sigma \phi_1(y_1) \right\| \leq N_2 (\omega_1 + \omega_2) \left( \|y - y_1\| + \left\| D^\delta y - D^\delta y_1 \right\| \right). \quad (3.14)$$

By (3.9) and (3.14), we can write

$$\|\phi_1(y) - \phi_1(y_1)\|_X \leq (N_1 + N_2) (\omega_1 + \omega_2) \left( \|y - y_1\| + \left\| D^\delta y - D^\delta y_1 \right\| \right). \quad (3.15)$$

With the same arguments as before, we have

$$\|\phi_2(x) - \phi_2(x_1)\|_Y \leq (N_3 + N_4) (\varpi_1 + \varpi_2) \left( \|x - x_1\| + \left\| D^\sigma x - D^\sigma x_1 \right\| \right). \quad (3.16)$$

Using (3.15) and (3.16), we can state that

$$\|\phi(x, y) - \phi(x_1, y_1)\|_{X \times Y} \leq \left[ \begin{array}{c} (N_1 + N_2) (\omega_1 + \omega_2) \\ + (N_3 + N_4) (\varpi_1 + \varpi_2) \end{array} \right] (\|(x - x_1, y - y_1)\|_{X \times Y}). \quad (3.17)$$

Thanks to (3.2), we conclude that  $\phi$  is contraction. As a consequence of Banach fixed point theorem, we deduce that  $\phi$  has a unique fixed point which is a solution of (1.1).

The second main result is based on Schaefer theorem. We have:

**Theorem 3.2.** *Suppose that (H1) and (H3) are satisfied. Then, the problem (1.1) has at least one solution on  $J$ .*

**Proof: A:** Thanks to (H1), we can state that the operator  $\phi$  is continuous on  $X \times Y$ .

**B:** We will prove that  $\phi$  maps bounded sets into bounded sets in  $X \times Y$ .

So, taking  $\rho > 0$ , and  $(x, y) \in B_\rho := \{(x, y) \in X \times Y; \|(x, y)\|_{X \times Y} \leq \rho\}$ , then for each  $t \in J$ , we have:

$$\begin{aligned} |\phi_1 y(t)| &\leq \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} \left| f(s, y(s), D^\delta y(s)) \right| ds \\ &+ \frac{|\lambda_1|t}{|\lambda_1\eta-1|\Gamma(\alpha)} \int_0^\eta (\eta-s)^{\alpha-1} \left| f(s, y(s), D^\delta y(s)) \right| ds \\ &+ \frac{t}{|\lambda_1\eta-1|\Gamma(\alpha)} \int_0^\eta (\eta-s)^{\alpha-1} \left| f(s, y(s), D^\delta y(s)) \right| ds \\ &+ \frac{|\lambda_2-\lambda_2\lambda_1\eta^3|t+|\lambda_2\lambda_1\eta-\lambda_2|t^3}{6|\lambda_1\eta-1||\lambda_2\xi-1|\Gamma(\alpha-2)} \int_0^\xi (\xi-s)^{\alpha-3} \left| f(s, y(s), D^\delta y(s)) \right| ds \\ &+ \frac{|1-\lambda_1\eta^3|t+|\lambda_1\eta-1|t^3}{6|\lambda_1\eta-1||\lambda_2\xi-1|\Gamma(\alpha-2)} \int_0^1 (1-s)^{\alpha-3} \left| f(s, y(s), D^\delta y(s)) \right| ds. \end{aligned} \quad (3.18)$$

The condition (H3) implies that

$$\begin{aligned} |\phi_1 y(t)| &\leq \frac{L_1(|\lambda_1 \eta - 1| |\lambda_1| \eta^\alpha + 1)}{|\lambda_1 \eta - 1| \Gamma(\alpha + 1)} + \frac{L_1 \left[ (|\lambda_2 - \lambda_2 \lambda_1 \eta^3| + |\lambda_2 \lambda_1 \eta - \lambda_2|) \xi^{\alpha-2} + (|1 - \lambda_1 \eta^3| + |\lambda_1 \eta - 1|) \right]}{6 |\lambda_1 \eta - 1| |\lambda_2 \xi - 1| \Gamma(\alpha - 1)} \\ &\leq L_1 \left[ \frac{\frac{|\lambda_1 \eta - 1| |\lambda_1| \eta^\alpha + 1}{|\lambda_1 \eta - 1| \Gamma(\alpha + 1)}}{+ \frac{(|\lambda_2 - \lambda_2 \lambda_1 \eta^3| + |\lambda_2 \lambda_1 \eta - \lambda_2|) \xi^{\alpha-2} + |1 - \lambda_1 \eta^3| + |\lambda_1 \eta - 1|}{6 |\lambda_1 \eta - 1| |\lambda_2 \xi - 1| \Gamma(\alpha - 1)}} \right]. \end{aligned} \quad (3.19)$$

Then,

$$\|\phi_1(y)\| \leq L_1 N_1. \quad (3.20)$$

For  $D^\sigma$ , we have the following inequalities

$$\begin{aligned} |D^\sigma \phi_1 y(t)| &\leq \frac{1}{\Gamma(\alpha - \sigma)} \int_0^t (t - s)^{\alpha - \sigma - 1} \left| f(s, y(s), D^\delta y(s)) \right| ds \\ &\quad + \frac{|\lambda_1| t^{1-\sigma}}{|\lambda_1 \eta - 1| \Gamma(\alpha) \Gamma(2 - \sigma)} \int_0^\eta (\eta - s)^{\alpha - 1} \left| f(s, y(s), D^\delta y(s)) \right| ds \\ &\quad + \frac{t^{1-\sigma}}{(|\lambda_1 \eta - 1|) \Gamma(\alpha) \Gamma(2 - \sigma)} \int_0^1 (1 - s)^{\alpha - 1} \left| f(s, y(s), D^\delta y(s)) \right| ds \\ &\quad + \frac{1}{\Gamma(\alpha - 2)} \left( \frac{|\lambda_2 - \lambda_2 \lambda_1 \eta^3| t^{1-\sigma}}{6 |\lambda_1 \eta - 1| |\lambda_2 \xi - 1| \Gamma(2 - \sigma)} + \frac{|\lambda_2 \lambda_1 \eta - \lambda_2| t^{3-\sigma}}{|\lambda_1 \eta - 1| |\lambda_2 \xi - 1| \Gamma(4 - \sigma)} \right) \int_0^\xi (\xi - s)^{\alpha - 3} \left| f(s, y(s), D^\delta y(s)) \right| ds \\ &\quad + \frac{1}{\Gamma(\alpha - 2)} \left( \frac{|1 - \lambda_1 \eta^3| t^{1-\sigma}}{6 |\lambda_1 \eta - 1| |\lambda_2 \xi - 1| \Gamma(2 - \sigma)} + \frac{|\lambda_1 \eta - 1| t^{3-\sigma}}{|\lambda_1 \eta - 1| |\lambda_2 \xi - 1| \Gamma(4 - \sigma)} \right) \int_0^1 (1 - s)^{\alpha - 3} \left| f(s, y(s), D^\delta y(s)) \right| ds. \end{aligned} \quad (3.21)$$

By (H3) again, yields the following formula

$$\begin{aligned} |D^\sigma \phi_1 y(t)| &\leq L_1 \left[ \frac{1}{\Gamma(\alpha - \sigma + 1)} + \frac{|\lambda_1| \eta^\alpha + 1}{|\lambda_1 \eta - 1| \Gamma(\alpha + 1) \Gamma(2 - \sigma)} \right] \\ &\quad + L_1 \left[ \frac{|\lambda_2 - \lambda_2 \lambda_1 \eta^3| \xi^{\alpha-2} + |1 - \lambda_1 \eta^3|}{6 |\lambda_1 \eta - 1| |\lambda_2 \xi - 1| \Gamma(\alpha - 1) \Gamma(2 - \sigma)} + \frac{|\lambda_2 \lambda_1 \eta - \lambda_2| \xi^{\alpha-2} + |\lambda_1 \eta - 1|}{|\lambda_1 \eta - 1| |\lambda_2 \xi - 1| \Gamma(\alpha - 1) \Gamma(4 - \sigma)} \right] \\ &\leq L_1 \left[ \frac{\frac{1}{\Gamma(\alpha - \sigma + 1)} + \frac{|\lambda_1| \eta^\alpha + 1}{|\lambda_1 \eta - 1| \Gamma(\alpha + 1) \Gamma(2 - \sigma)}}{+ \frac{|\lambda_2 - \lambda_2 \lambda_1 \eta^3| \xi^{\alpha-2} + |1 - \lambda_1 \eta^3|}{6 |\lambda_1 \eta - 1| |\lambda_2 \xi - 1| \Gamma(\alpha - 1) \Gamma(2 - \sigma)} + \frac{|\lambda_2 \lambda_1 \eta - \lambda_2| \xi^{\alpha-2} + |\lambda_1 \eta - 1|}{|\lambda_1 \eta - 1| |\lambda_2 \xi - 1| \Gamma(\alpha - 1) \Gamma(4 - \sigma)}} \right]. \end{aligned} \quad (3.22)$$

Hence, we can write

$$\|D^\sigma \phi_1(y)\| \leq L_1 N_2. \quad (3.23)$$

Using (3.20) and (3.23), we obtain

$$\|\phi_1(y)\|_X \leq L_1 (N_1 + N_2). \quad (3.24)$$



As before, we obtain

$$\|\phi_2(x)\|_Y \leq L_2(N_3 + N_4). \quad (3.25)$$

By (3.24) and (3.25), we get

$$\|\phi(x, y)\|_{X \times Y} \leq L_1(N_1 + N_2) + L_2(N_3 + N_4). \quad (3.26)$$

Therefore,

$$\|\phi(x, y)\|_{X \times Y} < \infty. \quad (3.27)$$

**C:** Now, we prove the equi-continuity of  $\phi$ .

Let us take  $(x, y) \in B_\rho$ , and  $t_1, t_2 \in J$ , with  $t_1 < t_2$ . We have:

$$\begin{aligned} |\phi_{1Y}(t_2) - \phi_{1Y}(t_1)| &\leq \frac{1}{\Gamma(\alpha)} \int_0^{t_1} \left( (t_1 - s)^{\alpha-1} - (t_2 - s)^{\alpha-1} \right) \left| f(s, y(s), D^\delta y(s)) \right| ds \\ &\quad + \frac{1}{\Gamma(\alpha)} \int_{t_1}^{t_2} (t_2 - s)^{\alpha-1} \left| f(s, y(s), D^\delta y(s)) \right| ds \\ &\quad + \frac{|\lambda_1|(t_2 - t_1)}{|\lambda_1\eta - 1|\Gamma(\alpha)} \int_0^\eta (\eta - s)^{\alpha-1} \left| f(s, y(s), D^\delta y(s)) \right| ds \\ &\quad + \frac{(t_1 - t_2)}{|\lambda_1\eta - 1|\Gamma(\alpha)} \int_0^1 (1 - s)^{\alpha-1} \left| f(s, y(s), D^\delta y(s)) \right| ds \\ &\quad + \frac{|\lambda_2 - \lambda_2\lambda_1\eta^3|(t_2 - t_1) + |\lambda_2\lambda_1\eta - \lambda_2|(t_2^3 - t_1^3)}{6|\lambda_1\eta - 1||\lambda_2\xi - 1|\Gamma(\alpha-2)} \int_0^\xi (\xi - s)^{\alpha-3} \left| f(s, y(s), D^\delta y(s)) \right| ds \\ &\quad + \frac{|1 - \lambda_1\eta^3|(t_1 - t_2) + |\lambda_1\eta - 1|(t_1^3 - t_2^3)}{6|\lambda_1\eta - 1||\lambda_2\xi - 1|\Gamma(\alpha-2)} \int_0^1 (1 - s)^{\alpha-3} \left| f(s, y(s), D^\delta y(s)) \right| ds \\ &\leq \frac{L_1(t_1^\alpha - t_2^\alpha + 2(t_2^\alpha - t_1^\alpha))}{\Gamma(\alpha+1)} + \frac{L_1|\lambda_1|\eta^\alpha(t_2 - t_1)}{|\lambda_1\eta - 1|\Gamma(\alpha+1)} + \frac{L_1(t_1 - t_2)}{|\lambda_1\eta - 1|\Gamma(\alpha+1)} \\ &\quad + \frac{L_1|\lambda_2 - \lambda_2\lambda_1\eta^3|\xi^{\alpha-2}(t_2 - t_1) + L_1|\lambda_2\lambda_1\eta - \lambda_2|\xi^{\alpha-2}(t_2^3 - t_1^3)}{6|\lambda_1\eta - 1||\lambda_2\xi - 1|\Gamma(\alpha-1)} \\ &\quad + \frac{L_1|1 - \lambda_1\eta^3|(t_1 - t_2) + L_1|\lambda_1\eta - 1|(t_1^3 - t_2^3)}{6|\lambda_1\eta - 1||\lambda_2\xi - 1|\Gamma(\alpha-1)}. \end{aligned} \quad (3.28)$$

Therefore,

$$\begin{aligned} |\phi_{1Y}(t_2) - \phi_{1Y}(t_1)| &\leq L_1 \left[ \frac{|\lambda_1\eta - 1| + |\lambda_1|\eta^\alpha}{|\lambda_1\eta - 1|\Gamma(\alpha+1)} + \frac{|\lambda_2 - \lambda_2\lambda_1\eta^3|\xi^{\alpha-2}}{6|\lambda_1\eta - 1||\lambda_2\xi - 1|\Gamma(\alpha-1)} \right] (t_2 - t_1) \\ &\quad + L_1 \left[ \frac{1}{|\lambda_1\eta - 1|\Gamma(\alpha+1)} + \frac{|1 - \lambda_1\eta^3|}{6|\lambda_1\eta - 1||\lambda_2\xi - 1|\Gamma(\alpha-1)} \right] (t_1 - t_2) \\ &\quad + L_1 \left[ \frac{|\lambda_2\lambda_1\eta - \lambda_2|\xi^{\alpha-2}}{6|\lambda_1\eta - 1||\lambda_2\xi - 1|\Gamma(\alpha-1)} \right] (t_2^3 - t_1^3) + \frac{L_1|\lambda_1\eta - 1|}{6|\lambda_1\eta - 1||\lambda_2\xi - 1|\Gamma(\alpha-1)} (t_1^3 - t_2^3) \\ &\quad + \frac{L_1}{\Gamma(\alpha+1)} (t_1^\alpha - t_2^\alpha) + \frac{2L_1}{\Gamma(\alpha+1)} (t_2 - t_1)^\alpha. \end{aligned} \quad (3.29)$$

We have also

$$\begin{aligned}
 |D^\sigma \phi_{1y}(t_2) - D^\sigma \phi_{1y}(t_1)| &\leq \frac{1}{\Gamma(\alpha-\sigma)} \int_0^{t_1} ((t_1-s)^{\alpha-\sigma-1} - (t_2-s)^{\alpha-\sigma-1}) |f(s, y(s), D^\delta y(s))| ds \\
 &\quad + \frac{1}{\Gamma(\alpha-\sigma)} \int_{t_1}^{t_2} (t_2-s)^{\alpha-\sigma-1} |f(s, y(s), D^\delta y(s))| ds \\
 &\quad + \frac{|\lambda_1|(t_2^{1-\sigma} - t_1^{1-\sigma})}{|\lambda_1\eta-1|\Gamma(\alpha)\Gamma(2-\sigma)} \int_0^\eta (\eta-s)^{\alpha-1} |f(s, y(s), D^\delta y(s))| ds \\
 &\quad + \frac{(t_1^{1-\sigma} - t_2^{1-\sigma})}{|\lambda_1\eta-1|\Gamma(\alpha)\Gamma(2-\sigma)} \int_0^1 (1-s)^{\alpha-1} |f(s, y(s), D^\delta y(s))| ds \\
 &\quad + \left[ \frac{|\lambda_2 - \lambda_2\lambda_1\eta^3|(t_2^{1-\sigma} - t_1^{1-\sigma})}{6|\lambda_1\eta-1||\lambda_2\xi-1|\Gamma(\alpha-2)\Gamma(2-\sigma)} \right. \\
 &\quad \left. + \frac{|\lambda_2\lambda_1\eta-\lambda_2|(t_2^{3-\sigma} - t_1^{3-\sigma})}{|\lambda_1\eta-1||\lambda_2\xi-1|\Gamma(\alpha-2)\Gamma(4-\sigma)} \right] \int_0^\xi (\xi-s)^{\alpha-3} |f(s, y(s), D^\delta y(s))| ds \\
 &\quad + \left[ \frac{|1-\lambda_1\eta^3|(t_1^{1-\sigma} - t_2^{1-\sigma})}{6|\lambda_1\eta-1||\lambda_2\xi-1|\Gamma(\alpha-2)\Gamma(2-\sigma)} \right. \\
 &\quad \left. + \frac{|\lambda_1\eta-1|(t_1^{3-\sigma} - t_2^{3-\sigma})}{|\lambda_1\eta-1||\lambda_2\xi-1|\Gamma(\alpha-2)\Gamma(2-\sigma)} \right] \int_0^1 (1-s)^{\alpha-3} |f(s, y(s), D^\delta y(s))| ds.
 \end{aligned}
 \tag{3.30}$$

The condition (H3) implies that

$$\begin{aligned}
 |D^\sigma \phi_{1y}(t_2) - D^\sigma \phi_{1y}(t_1)| &\leq \frac{L_1}{\Gamma(\alpha-\sigma+1)} (t_1^{\alpha-\sigma} - t_2^{\alpha-\sigma} + 2(t_2 - t_1)^{\alpha-\sigma}) \\
 + L_1 &\left[ \frac{\frac{|\lambda_1|\eta^{\alpha+1}}{|\lambda_1\eta-1|\Gamma(\alpha+1)\Gamma(2-\sigma)}}{\frac{|\lambda_2-\lambda_2\lambda_1\eta^3|\xi^{\alpha-2}}{6|\lambda_1\eta-1||\lambda_2\xi-1|\Gamma(\alpha-1)\Gamma(2-\sigma)}} \right] (t_2^{1-\sigma} - t_1^{1-\sigma}) + L_1 \left[ \frac{\frac{1}{|\lambda_1\eta-1|\Gamma(\alpha+1)\Gamma(2-\sigma)}}{\frac{|1-\lambda_1\eta^3|}{6|\lambda_1\eta-1||\lambda_2\xi-1|\Gamma(\alpha-1)\Gamma(2-\sigma)}} \right] (t_1^{1-\sigma} - t_2^{1-\sigma}) \\
 &\quad + \frac{L_1|\lambda_2\lambda_1\eta-\lambda_2|\xi^{\alpha-2}}{|\lambda_1\eta-1||\lambda_2\xi-1|\Gamma(\alpha-1)\Gamma(4-\sigma)} (t_2^{3-\sigma} - t_1^{3-\sigma}) + \frac{L_1|\lambda_1\eta-1|}{|\lambda_1\eta-1||\lambda_2\xi-1|\Gamma(\alpha-1)\Gamma(4-\sigma)} (t_1^{3-\sigma} - t_2^{3-\sigma}).
 \end{aligned}
 \tag{3.31}$$

The inequalities (3.29) and (3.31) imply that:

$$\begin{aligned}
\|\phi_1 y(t_2) - \phi_1 y(t_1)\|_X &\leq L_1 \left[ \frac{|\lambda_1 \eta - 1| + |\lambda_1| \eta^\alpha}{|\lambda_1 \eta - 1| \Gamma(\alpha + 1)} + \frac{|\lambda_2 - \lambda_2 \lambda_1 \eta^3| \xi^{\alpha-2}}{6|\lambda_1 \eta - 1| |\lambda_2 \xi - 1| \Gamma(\alpha - 1)} \right] (t_2 - t_1) \\
&+ L_1 \left[ \frac{1}{|\lambda_1 \eta - 1| \Gamma(\alpha + 1)} + \frac{|1 - \lambda_1 \eta^3|}{6|\lambda_1 \eta - 1| |\lambda_2 \xi - 1| \Gamma(\alpha - 1)} \right] (t_1 - t_2) + L_1 \left[ \frac{|\lambda_2 \lambda_1 \eta - \lambda_2| \xi^{\alpha-2}}{6|\lambda_1 \eta - 1| |\lambda_2 \xi - 1| \Gamma(\alpha - 1)} \right] (t_2^3 - t_1^3) \\
&+ \frac{L_1 |\lambda_1 \eta - 1|}{6|\lambda_1 \eta - 1| |\lambda_2 \xi - 1| \Gamma(\alpha - 1)} (t_1^3 - t_2^3) + \frac{L_1}{\Gamma(\alpha + 1)} (t_1^\alpha - t_2^\alpha + 2(t_2 - t_1)^\alpha) \\
&+ \frac{L_1}{\Gamma(\alpha - \sigma + 1)} (t_1^{\alpha - \sigma} - t_2^{\alpha - \sigma} + 2(t_2 - t_1)^{\alpha - \sigma}) + L_1 \left[ \frac{\frac{|\lambda_1| \eta^{\alpha+1}}{|\lambda_1 \eta - 1| \Gamma(\alpha + 1) \Gamma(2 - \sigma)}}{\frac{|\lambda_2 - \lambda_2 \lambda_1 \eta^3| \xi^{\alpha-2}}{6|\lambda_1 \eta - 1| |\lambda_2 \xi - 1| \Gamma(\alpha - 1) \Gamma(2 - \sigma)}} \right] (t_2^{1-\sigma} - t_1^{1-\sigma}) \\
&+ L_1 \left[ \frac{1}{|\lambda_1 \eta - 1| \Gamma(\alpha + 1) \Gamma(2 - \sigma)} + \frac{|1 - \lambda_1 \eta^3|}{6|\lambda_1 \eta - 1| |\lambda_2 \xi - 1| \Gamma(\alpha - 1) \Gamma(2 - \sigma)} \right] (t_1^{1-\sigma} - t_2^{1-\sigma}) \\
&+ \frac{L_1 |\lambda_2 \lambda_1 \eta - \lambda_2| \xi^{\alpha-2}}{|\lambda_1 \eta - 1| |\lambda_2 \xi - 1| \Gamma(\alpha - 1) \Gamma(4 - \sigma)} (t_2^{3-\sigma} - t_1^{3-\sigma}) + \frac{L_1 |\lambda_1 \eta - 1|}{|\lambda_1 \eta - 1| |\lambda_2 \xi - 1| \Gamma(\alpha - 1) \Gamma(4 - \sigma)} (t_1^{3-\sigma} - t_2^{3-\sigma}).
\end{aligned} \tag{3.32}$$

With the same arguments as before, we can write

$$\begin{aligned}
\|\phi_2 x(t_2) - \phi_2 x(t_1)\|_Y &\leq L_2 \left[ \frac{|\lambda_1 \eta - 1| + |\lambda_1| \eta^\beta}{|\lambda_1 \eta - 1| \Gamma(\beta + 1)} + \frac{|\lambda_2 - \lambda_2 \lambda_1 \eta^3| \xi^{\beta-2}}{6|\lambda_1 \eta - 1| |\lambda_2 \xi - 1| \Gamma(\beta - 1)} \right] (t_2 - t_1) \\
&+ L_2 \left[ \frac{1}{|\lambda_1 \eta - 1| \Gamma(\beta + 1)} + \frac{|1 - \lambda_1 \eta^3|}{6|\lambda_1 \eta - 1| |\lambda_2 \xi - 1| \Gamma(\beta - 1)} \right] (t_1 - t_2) + L_2 \left[ \frac{|\lambda_2 \lambda_1 \eta - \lambda_2| \xi^{\beta-2}}{6|\lambda_1 \eta - 1| |\lambda_2 \xi - 1| \Gamma(\beta - 1)} \right] (t_2^3 - t_1^3) \\
&+ \frac{L_2 |\lambda_1 \eta - 1|}{6|\lambda_1 \eta - 1| |\lambda_2 \xi - 1| \Gamma(\beta - 1)} (t_1^3 - t_2^3) + \frac{L_2}{\Gamma(\beta + 1)} (t_1^\beta - t_2^\beta + 2(t_2 - t_1)^\beta) \\
&+ \frac{L_2}{\Gamma(\alpha - \beta + 1)} (t_1^{\beta - \delta} - t_2^{\beta - \delta} + 2(t_2 - t_1)^{\beta - \delta}) + L_2 \left[ \frac{\frac{|\lambda_1| \eta^{\beta+1}}{|\lambda_1 \eta - 1| \Gamma(\beta + 1) \Gamma(2 - \delta)}}{\frac{|\lambda_2 - \lambda_2 \lambda_1 \eta^3| \xi^{\beta-2}}{6|\lambda_1 \eta - 1| |\lambda_2 \xi - 1| \Gamma(\beta - 1) \Gamma(2 - \delta)}} \right] (t_2^{1-\delta} - t_1^{1-\delta}) \\
&+ L_2 \left[ \frac{1}{|\lambda_1 \eta - 1| \Gamma(\beta + 1) \Gamma(2 - \delta)} + \frac{|1 - \lambda_1 \eta^3|}{6|\lambda_1 \eta - 1| |\lambda_2 \xi - 1| \Gamma(\beta - 1) \Gamma(2 - \delta)} \right] (t_1^{1-\delta} - t_2^{1-\delta}) \\
&+ \frac{L_2 |\lambda_2 \lambda_1 \eta - \lambda_2| \xi^{\beta-2}}{|\lambda_1 \eta - 1| |\lambda_2 \xi - 1| \Gamma(\beta - 1) \Gamma(4 - \delta)} (t_2^{3-\delta} - t_1^{3-\delta}) + \frac{L_2 |\lambda_1 \eta - 1|}{|\lambda_1 \eta - 1| |\lambda_2 \xi - 1| \Gamma(\beta - 1) \Gamma(4 - \delta)} (t_1^{3-\delta} - t_2^{3-\delta}).
\end{aligned} \tag{3.33}$$

Thanks to (3.32) and (3.33), we can state that  $\|\phi(x, y)(t_2) - \phi(x, y)(t_1)\|_{X \times Y} \rightarrow 0$  as  $t_2 \rightarrow t_1$ . Combining **A**, **B**, **C** and using Arzela-Ascoli theorem, we conclude that  $\phi$  is completely continuous operator.

**D:** We shall show that

$$\Omega := \{(x, y) \in X \times Y, (x, y) = \mu \phi(x, y), 0 < \mu < 1\}, \tag{3.34}$$

is a bounded set.

Let  $(x, y) \in \Omega$ , then  $(x, y) = \mu \phi(x, y)$ , for some  $0 < \mu < 1$ . Thus, for each  $t \in J$ , we have:

$$y(t) = \mu \phi_1 y(t), x(t) = \mu \phi_2 x(t).$$

Therefore,

$$\begin{aligned} \frac{1}{\mu} |y(t)| \leq & \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} \left| f(s, y(s), D^\delta(s)) \right| ds \\ & + \frac{|\lambda_1|t}{|\lambda_1\eta-1|\Gamma(\alpha)} \int_0^\eta (\eta-s)^{\alpha-1} \left| f(s, y(s), D^\delta(s)) \right| ds \\ & + \frac{t}{|\lambda_1\eta-1|\Gamma(\alpha)} \int_0^\eta (\eta-s)^{\alpha-1} \left| f(s, y(s), D^\delta(s)) \right| ds \\ & + \frac{|\lambda_2-\lambda_2\lambda_1\eta^3|t+|\lambda_2\lambda_1\eta-\lambda_2|t^3}{6|\lambda_1\eta-1||\lambda_2\xi-1|\Gamma(\alpha-2)} \int_0^\xi (\xi-s)^{\alpha-3} \left| f(s, y(s), D^\delta(s)) \right| ds \\ & + \frac{|1-\lambda_1\eta^3|t+|\lambda_1\eta-1|t^3}{6|\lambda_1\eta-1||\lambda_2\xi-1|\Gamma(\alpha-2)} \int_0^1 (1-s)^{\alpha-3} \left| f(s, y(s), D^\delta(s)) \right| ds. \end{aligned} \quad (3.35)$$

Thanks to (H3), we can write

$$\begin{aligned} \frac{1}{\mu} |y(t)| \leq & \frac{L_1(|\lambda_1\eta-1|+|\lambda_1|\eta^\alpha+1)}{|\lambda_1\eta-1|\Gamma(\alpha+1)} \\ & + \frac{L_1(|\lambda_2-\lambda_2\lambda_1\eta^3|+|\lambda_2\lambda_1\eta-\lambda_2|)\xi^{\alpha-2}+|1-\lambda_1\eta^3|+|\lambda_1\eta-1|}{6|\lambda_1\eta-1||\lambda_2\xi-1|\Gamma(\alpha-1)}. \end{aligned} \quad (3.36)$$

Thus,

$$|y(t)| \leq \mu L_1 \left[ \frac{(|\lambda_1\eta-1|+|\lambda_1|\eta^\alpha+1)}{|\lambda_1\eta-1|\Gamma(\alpha+1)} + \frac{(|\lambda_2-\lambda_2\lambda_1\eta^3|+|\lambda_2\lambda_1\eta-\lambda_2|)\xi^{\alpha-2}+|1-\lambda_1\eta^3|+|\lambda_1\eta-1|}{6|\lambda_1\eta-1||\lambda_2\xi-1|\Gamma(\alpha-1)} \right]. \quad (3.37)$$

Hence,

$$|y(t)| \leq \mu N_1 L_1, t \in J. \quad (3.38)$$

On the other hand,

$$\begin{aligned} \frac{1}{\mu} |D^\sigma y(t)| \leq & \frac{1}{\Gamma(\alpha-\delta)} \int_0^t (t-s)^{\alpha-\sigma-1} \left| f(s, y(s), D^\delta(s)) \right| ds \\ & + \frac{|\lambda_1|t^{1-\sigma}}{|\lambda_1\eta-1|\Gamma(\alpha)\Gamma(2-\sigma)} \int_0^\eta (\eta-s)^{\alpha-1} \left| f(s, y(s), D^\delta(s)) \right| ds \\ & + \frac{t^{1-\sigma}}{|\lambda_1\eta-1|\Gamma(\alpha)\Gamma(2-\sigma)} \int_0^\eta (\eta-s)^{\alpha-1} \left| f(s, y(s), D^\delta(s)) \right| ds \\ & + \left[ \frac{|\lambda_2-\lambda_2\lambda_1\eta^3|t^{1-\sigma}}{6|\lambda_1\eta-1||\lambda_2\xi-1|\Gamma(\alpha-2)\Gamma(2-\sigma)} + \frac{|\lambda_2\lambda_1\eta-\lambda_2|t^{3-\sigma}}{|\lambda_1\eta-1||\lambda_2\xi-1|\Gamma(\alpha-2)\Gamma(4-\sigma)} \right] \int_0^\xi (\xi-s)^{\alpha-3} \left| f(s, y(s), D^\delta(s)) \right| ds \\ & + \left[ \frac{|1-\lambda_1\eta^3|t^{1-\sigma}}{6|\lambda_1\eta-1||\lambda_2\xi-1|\Gamma(\alpha-2)\Gamma(2-\sigma)} + \frac{|\lambda_1\eta-1|t^{3-\sigma}}{|\lambda_1\eta-1||\lambda_2\xi-1|\Gamma(\alpha-2)\Gamma(4-\sigma)} \right] \int_0^1 (1-s)^{\alpha-3} \left| f(s, y(s), D^\delta(s)) \right| ds. \end{aligned} \quad (3.39)$$

Thanks to (H3), we have

$$\begin{aligned} \frac{1}{\mu} |D^\sigma y(t)| \leq & L_1 \left[ \frac{1}{\Gamma(\alpha-\sigma+1)} + \frac{|\lambda_1|\eta^\alpha+1}{|\lambda_1\eta-1|\Gamma(\alpha+1)\Gamma(2-\sigma)} \right] \\ & + L_1 \left[ \frac{|\lambda_2-\lambda_2\lambda_1\eta^3|\xi^{\alpha-2}+|1-\lambda_1\eta^3|}{6|\lambda_1\eta-1||\lambda_2\xi-1|\Gamma(\alpha-1)\Gamma(2-\sigma)} + \frac{|\lambda_2\lambda_1\eta-\lambda_2|\xi^{\alpha-2}+|\lambda_1\eta-1|}{|\lambda_1\eta-1||\lambda_2\xi-1|\Gamma(\alpha-1)\Gamma(4-\sigma)} \right]. \end{aligned} \quad (3.40)$$

Therefore,

$$\begin{aligned} |D^\sigma y(t)| \leq & \mu L_1 \left[ \frac{1}{\Gamma(\alpha-\sigma+1)} + \frac{|\lambda_1|\eta^\alpha+1}{|\lambda_1\eta-1|\Gamma(\alpha+1)\Gamma(2-\sigma)} \right] \\ & + \mu L_1 \left[ \frac{|\lambda_2-\lambda_2\lambda_1\eta^3|\xi^{\alpha-2}+|1-\lambda_1\eta^3|}{6|\lambda_1\eta-1||\lambda_2\xi-1|\Gamma(\alpha-1)\Gamma(2-\sigma)} + \frac{|\lambda_2\lambda_1\eta-\lambda_2|\xi^{\alpha-2}+|\lambda_1\eta-1|}{|\lambda_1\eta-1||\lambda_2\xi-1|\Gamma(\alpha-1)\Gamma(4-\sigma)} \right]. \end{aligned} \quad (3.41)$$

Thus,

$$|D^\beta y(t)| \leq \mu L_1 N_2, t \in J. \quad (3.42)$$

From (3.38) and (3.42), we get

$$\|y\|_X \leq \mu L_1 (N_1 + N_2). \quad (3.43)$$

Analogously, we can obtain

$$\|x\|_Y \leq \mu L_2 (N_3 + N_4). \quad (3.44)$$

It follows from (3.43) and (3.4) that

$$\|(x, y)\|_{X \times Y} \leq \mu L_1 (N_1 + N_2) + \mu L_2 (N_3 + N_4). \quad (3.45)$$

Hence,

$$\|\phi(x, y)\|_{X \times Y} < \infty. \quad (3.46)$$

This shows that the set  $\Omega$  is bounded. Thanks to **A**, **B**, **C** and **D**, we conclude that  $\phi$  has at least one fixed point. Theorem 3.2 is thus proved.

## 4. Examples

**Example 4.1.** Let us consider the coupled equations:

$$\begin{aligned} D^{\frac{7}{2}} x(t) + \frac{|y(t)|}{7(\pi t^2+3)^2(2+|y(t)|)} + \frac{\sqrt{\pi}e^{-\pi t}|\cos(\pi t)| \left| D^{\frac{7}{3}} y(t) \right|}{7\pi(1+e^t)^2 \left( 2 + \left| D^{\frac{7}{3}} y(t) \right| \right)} &= 0, t \in [0, 1], \\ D^{\frac{11}{3}} y(t) + \frac{3\pi|x(t)|}{(5e^{t^2}+3\sqrt{\pi})(1+|x(t)|)} + \frac{\pi e^{-2\pi t} \left| D^{\frac{5}{2}} x(t) \right|}{5(t+3\sqrt{\pi})^2 \left( 1 + \left| D^{\frac{5}{2}} x(t) \right| \right)} &= 0, t \in [0, 1], \\ x(0) = 0, x(1) - \frac{3}{4}x\left(\frac{1}{3}\right) = 0, y(0) = 0, y(1) - \frac{3}{4}y\left(\frac{1}{3}\right) = 0, \\ x''(0) = 0, x''(1) - \frac{4}{5}x''\left(\frac{2}{3}\right) = 0, y''(0) = 0, y''(1) - \frac{4}{5}y''\left(\frac{2}{3}\right) = 0. \end{aligned} \quad (4.1)$$

It is clear that

$$f(t, x, y) = \frac{|x|}{7(\pi t^2 + 3)^2(2 + |x|)} + \frac{\sqrt{\pi}e^{-\pi t}|\cos(\pi t)||y|}{7\pi(1 + e^t)^2(2 + |y|)}, t \in [0, 1], x, y \in \mathbb{R},$$

$$g(t, x, y) = \frac{3\pi|x|}{(5e^{t^2} + 3\sqrt{\pi})(1 + |x|)} + \frac{\pi e^{-2\pi t}|y|}{5(t + 3\sqrt{\pi})^2(1 + |y|)}, t \in [0, 1], x, y \in \mathbb{R}.$$

For  $x, y, x_1, y_1 \in \mathbb{R}, t \in [0, 1]$ , we have

$$|f(t, x, y) - f(t, x_1, y_1)| \leq \frac{1}{7(\pi t^2 + 3)^2}|x - x_1| + \frac{\sqrt{\pi}e^{-\pi t}}{7\pi(1 + e^t)^2}|y - y_1|,$$

and

$$|g(t, x, y) - g(t, x_1, y_1)| \leq \frac{3\pi}{(5e^{t^2} + 3\sqrt{\pi})}|x - x_1| + \frac{\pi e^{-2\pi t}}{5(t + 3\sqrt{\pi})^2}|y - y_1|.$$

Hence,

$$a_1(t) = \frac{1}{7(\pi t^2 + 3)^2}, b_1(t) = \frac{\sqrt{\pi}e^{-\pi t}}{7\pi(1 + e^t)^2},$$

and

$$a_2(t) = \frac{3\pi}{5e^{t^2} + 3\sqrt{\pi}}, b_2(t) = \frac{\pi e^{-2\pi t}}{5(t + 3\sqrt{\pi})^2}.$$

These imply that

$$\omega_1 = \sup_{t \in [0, 1]} a_1(t) = \frac{1}{63}, \omega_2 = \sup_{t \in [0, 1]} b_1(t) = \frac{\sqrt{\pi}}{28\pi},$$

$$\varpi_1 = \sup_{t \in [0, 1]} a_2(t) = \frac{3\pi}{5 + 3\sqrt{\pi}}, \varpi_2 = \sup_{t \in [0, 1]} b_2(t) = \frac{1}{45},$$

$$N_1 = 1, 08935, N_2 = 3, 444, N_3 = 0, 77571, N_4 = 2, 51754,$$

and,

$$(N_1 + N_2)(\omega_1 + \omega_2) + (N_3 + N_4)(\varpi_1 + \varpi_2) = 0, 16329 + 0, 36466 = 0, 52795 < 1.$$

So by Theorem 3.1, the problem (4.1) has a unique solution  $(x, y)$  on  $[0, 1]$ .

**Example 4.2.** The following example illustrates Theorem 3.2. We take:

$$\begin{aligned} D^{\frac{15}{4}} x(t) + \frac{1}{(t^2+1)\left(2+\left|D^{\frac{7}{3}} y(t)\right|\right)} + \frac{2e^{-t}|\cos(ty(t))|}{7(1+e^t)^2\left(2+\left|D^{\frac{7}{3}} y(t)\right|\right)} &= 0, t \in [0, 1], \\ D^{\frac{10}{3}} y(t) + \frac{1}{(e^{t^2}+1)(1+|x(t)|)} + \frac{e^{-t}}{(t+1)^2\left(1+\left|D^{\frac{5}{2}} x(t)\right|\right)} &= 0, t \in [0, 1], \\ x(0) = 0, x(1) - \frac{3}{4}x\left(\frac{1}{3}\right) = 0, y(0) = 0, y(1) - \frac{3}{4}y\left(\frac{1}{3}\right) &= 0, \\ x''(0) = 0, x''(1) - \frac{4}{5}x''\left(\frac{2}{3}\right) = 0, y''(0) = 0, y''(1) - \frac{4}{5}y''\left(\frac{2}{3}\right) &= 0. \end{aligned} \quad (4.2)$$

We have

$$f(t, x, y) = \frac{1}{(t^2 + 1)(2 + |y|)} + \frac{2e^{-t}|\cos(tx)|}{7(1 + e^t)^2(2 + |y|)}$$

and

$$g(t, x, y) = \frac{1}{(e^{t^2} + 1)(1 + |x|)} + \frac{e^{-t}}{(t + 1)^2(1 + |y|)}$$

So by Theorem 3.2, the problem (4.2) has at least one solution on  $[0, 1]$ .

## References

- Bengrine, M.E. and Z. Dahmani (2012). Boundary value problems for fractional differential equations. *Int. J. Open problems compt* **5**(4), 7–15.
- Delbosco, D. and L. Rodino (1996). Existence and uniqueness for a nonlinear fractional differential equation. *J. Math. Anal. Appl* **204**(3-4), 429–440.
- Diethelm, K. and G. Walz (1998). Numerical solution of fraction order differential equations by extrapolation. *Numer. Algorithms*. **16**(3), 231–253.
- Diethelm, K. and N.J. Ford (2002). Analysis of fractiona differential equations. *J. Math. Anal. Appl* **265**(2), 229–248.
- El-Sayed, A.M.A. (1998). Nonlinear functional differential equations of arbitrary orders. *Nonlinear Anal.* **33**(2), 181–186.
- Houas, M. and Z. Dahmani (2013). New fractional results for a boundary value problem with caputo derivative. *Int. J. Open Problems Compt. Math.* **2**(6), 30–42.
- Kilbas, A.A. and S.A. Marzan (2005). Nonlinear differential equation with the caputo fraction derivative in the space of continuously differentiable functions. *Differ. Equ.* **41**(1), 84–89.
- Lakshmikantham, V. and A.S. Vatsala (2008). Basic theory of fractional differential equations. *Nonlinear Anal.* **69**(8), 2677–2682.
- Mainardi, F. (1997). *Fractional calculus: Some basic problem in continuum and statistical mechanics*. Vol. Fractals and Fractional Calculus in Continuum Mechanics of *CISM International Centre for Mechanical Sciences*. Springer.
- Ntouyas, S.K. (2012). Existence results for first order boundary value problems for fractional differential equations and inclusions with fractional integral boundary conditions. *Journal of Fractional Calculus and Applications*. **3**(9), 1–14.
- Podlubny, I., I. Petras, B.M. Vinagre, P. O’leary and L. Dorcak (2002). Analogue realizations of fractional-order controllers. fractional order calculus and its applications. *Nonlinear Dynam* **29**(4), 281–296.

- Su, X. (2009). Boundary value problem for a coupled system of nonlinear fractional differential equations. *Applied Mathematics Letters*. **22**(1), 64–69.
- Yang, W. (2012). Positive solutions for a coupled system of nonlinear fractional differential equations with integral boundary conditions. *Comput. Math. Appl.* **63**, 288–297.
- Zhang, Y. (2011). Existence results for a coupled system of nonlinear fractional three-point boundary value problems at resonance. *Comput. Math. Appl.* **61**, 1032–1047.